

Space Information Flow

Zongpeng Li, August 17 2011

(joint work with Chuan Wu @ HKU)



Talk Outline

1. Space Information Flow in a NutShell
2. Space Information Flow: Motivation
3. Multiple Unicast in Space
4. Multicast in Space
5. Conclusion and Open Problems

Talk Outline

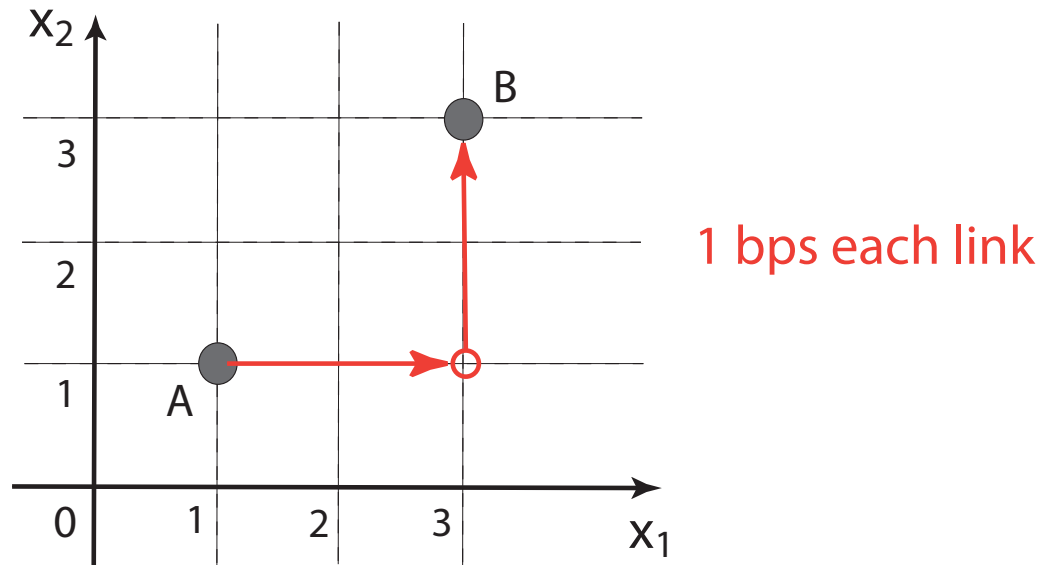
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1-1. Space Information Flow: The Problem

Space Information Flow:

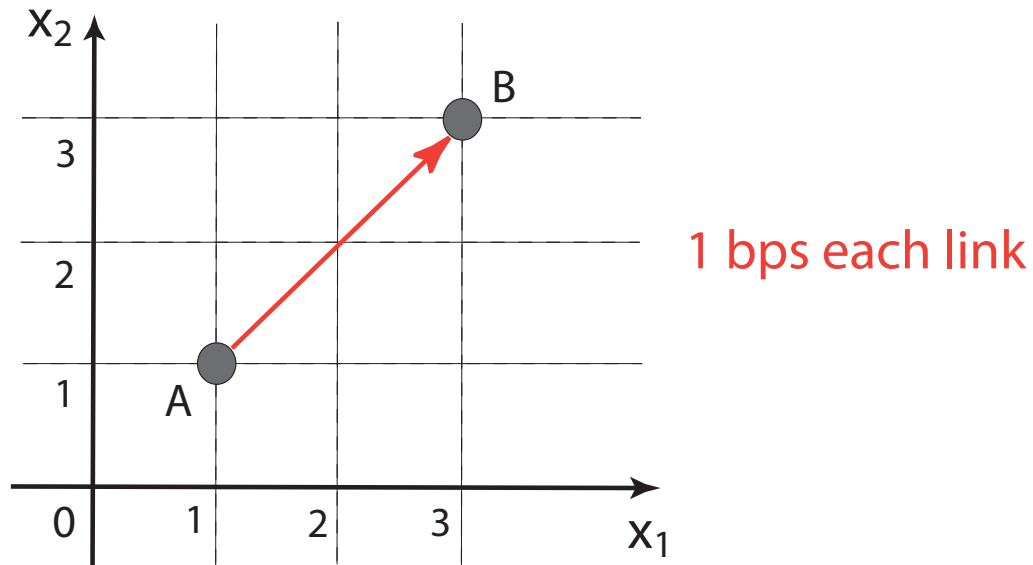
- Transmit information flows in space to satisfy end-to-end (unicast/multicast) communication demands among terminals at known coordinates
- Minimize $\sum_e(\mathbf{f}_e||e||)$
 - e : a ‘link’ employed by the flow \mathbf{f}
 - \mathbf{f}_e : flow rate at e
 - $||e||$: length of e

1-2. Space Information Flow: Unicast Example



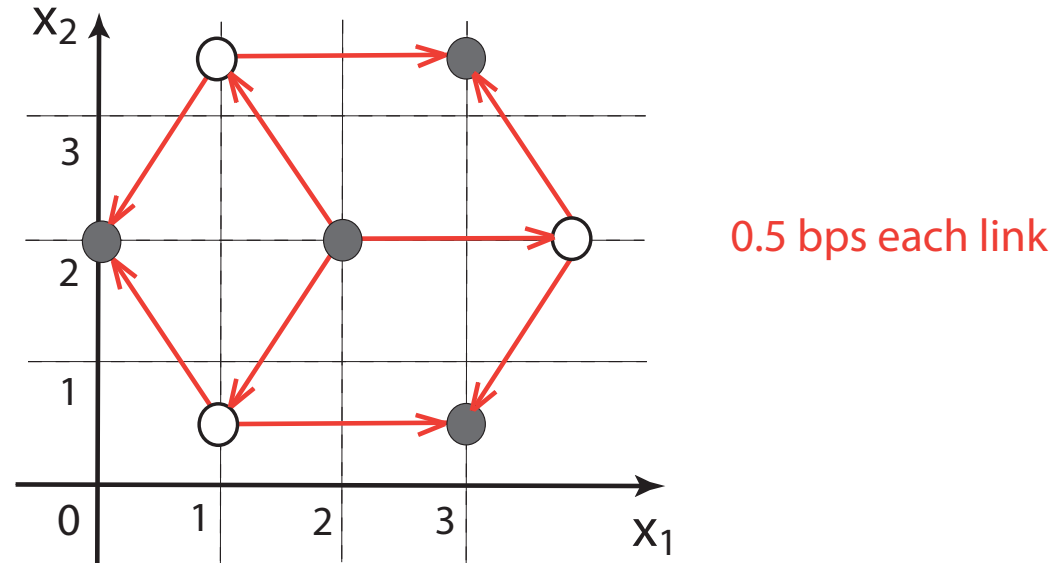
- Unicast demand: $A \rightarrow B$, 1 bps
- Cost: $(2m + 2m) \times 1 \text{ bit/sec} = 4 \text{ bit} \cdot \text{meter/sec}$

1-3. Space Information Flow: Unicast Example



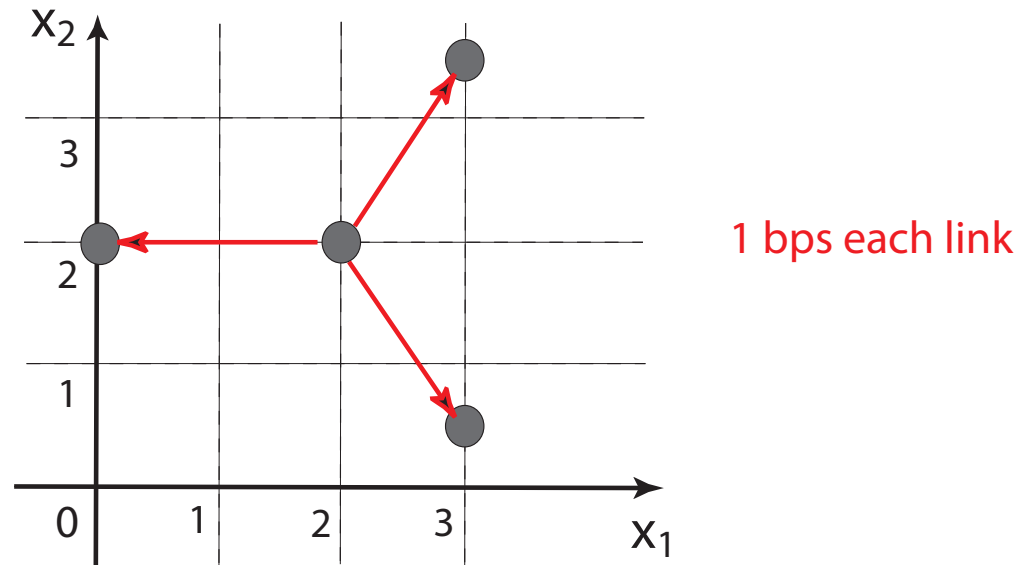
- Unicast demand: $A \rightarrow B$, 1 bps
- Cost: $(2\sqrt{2} \text{ m}) \times (1 \text{ bit}/\text{sec}) = 2.828 \text{ bit} \cdot \text{meter}/\text{sec}$

1-4. Space Information Flow: Multicast Example



- Multicast demand among terminal (black) nodes, 1 bps
- Cost: $(2 m) \times (0.5 \text{ bit/sec}) \times 9 = 9 \text{ bit} \cdot \text{meter/sec}$

1-5. Space Information Flow: Multicast Example



- Multicast demand among terminal (black) nodes, 1 bps
- Cost: $(2 m) \times (1 \text{ bit}/\text{sec}) \times 3 = 6 \text{ bit} \cdot \text{meter}/\text{sec}$

1-6. The (Geometric) Steiner Tree Problem

Gauss, 1836: *how can a railway network of minimal length which connects the four German cities **Bremen**, **Hamburg**, **Hannover**, and **Braunschweig** be created?*



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1.7. Space Information Flow vs. Steiner Tree

- SIF allows fractional flow rates
 - Steiner tree (implicit): each link has flow rate 1.0
- SIF allows information encoding (network coding)
 - Steiner tree: can model replication, but no coding
- SIF allows multiple sessions (with inter-session coding)

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2-1. Network Coding *vs.* Routing

The space model represents the ‘fairest’ paradigm for comparing network coding and routing.

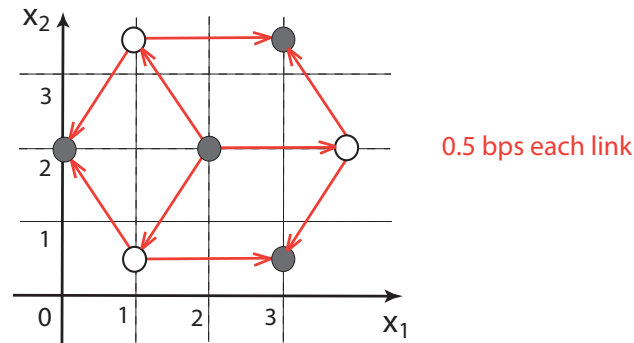
- **Directed networks:** contrived, tailored network topology and orientation favoring network coding
- **Undirected networks:** contrived, tailored network topology favoring network coding
- **Space:** network coding and routing are each free to design its own network topology and choose its own network orientation

2-2. Network Coding *vs.* Routing

The space model represents the ‘fairest’ paradigm for comparing network coding and routing.

	directed networks	undirected networks	space
multiple unicast	∞ $\Omega(n)$	conjectured: $\equiv 1$	$\equiv 1$
multicast	∞ $\Omega(\sqrt{n})$	≤ 2 $\geq 8/7$	≤ 1.155 (2-D) $\geq \alpha \in (1, 1.022)$

2-3. Information Network Design



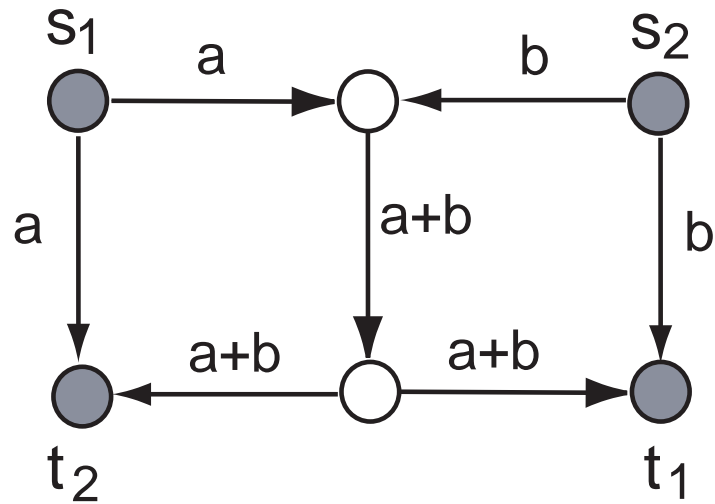
- A space information flow \mathbf{f} can be viewed as a **blue print** for constructing an information network
- A link e in \mathbf{f} — a communication cable to be laid
- Link flow rate \mathbf{f}_e — bandwidth capacity of the cable
- The longer the cable, the more expensive
- The wider the cable, the more expensive

Talk Outline

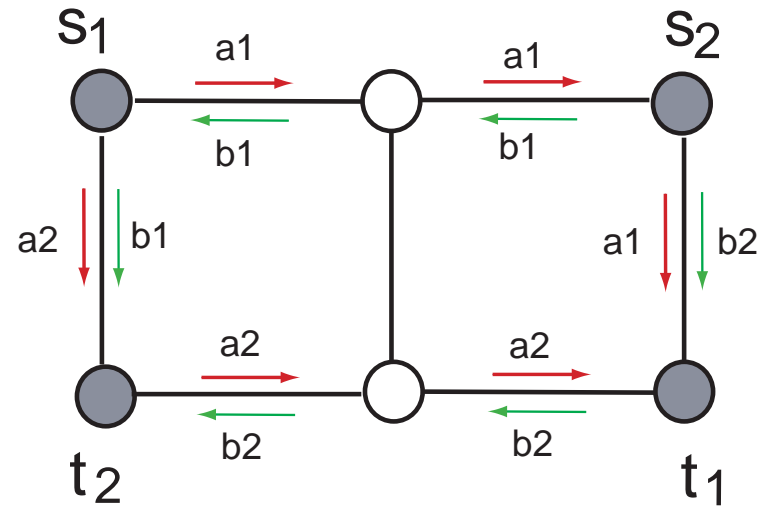
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3-1. Network Information Flow: Two Unicast

(A) each link flow rate is 1.0



(B) each link flow rate is 0.5



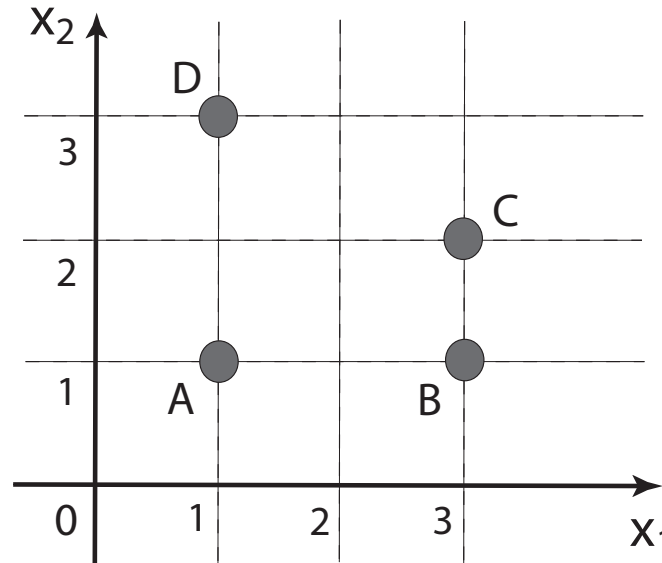
3-2. The Multiple Unicast Conjecture

Throughput domain: For k independent unicast sessions in a capacitated undirected network (G, \mathbf{c}) , a throughput vector \mathbf{r} is feasible with network coding if and only if it is feasible with routing.



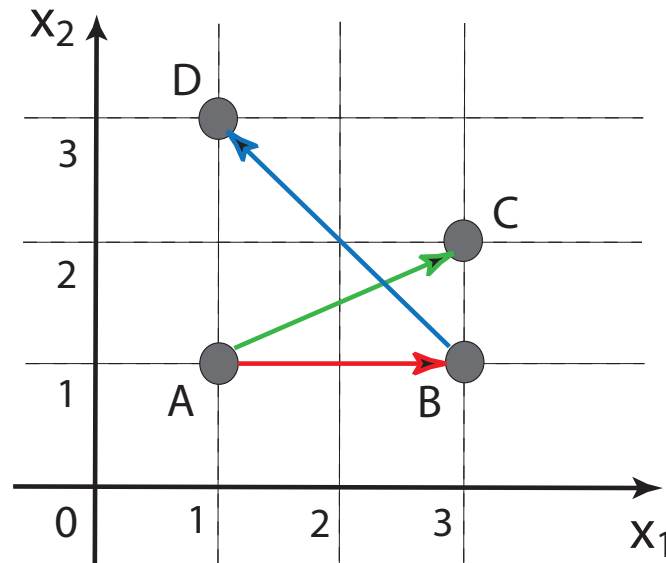
Cost domain: Let \mathbf{f} be the underlying flow vector of a network coding solution for k independent unicast sessions with throughput vector \mathbf{r} , in a cost-weighted undirected network (G, \mathbf{w}) . Then $\sum_e \mathbf{w}_e \mathbf{f}_e \geq \sum_i \mathbf{d}_i \mathbf{r}_i$, where \mathbf{d}_i is the shortest path distance between the sender and receiver of session i under metric \mathbf{w} .

3-3. Multiple Unicast in Space: The Problem



What's the best solution for three unicast: $A \rightarrow B$, $A \rightarrow C$, $B \rightarrow D$, each with unit throughput demand?

3-4. Multiple Unicast in Space: The Problem



$$Cost = \sum_i r_i d_i$$

Is optimal cost without network coding still optimal with network coding?

3-5. Multiple Unicast in Space: The Theorem

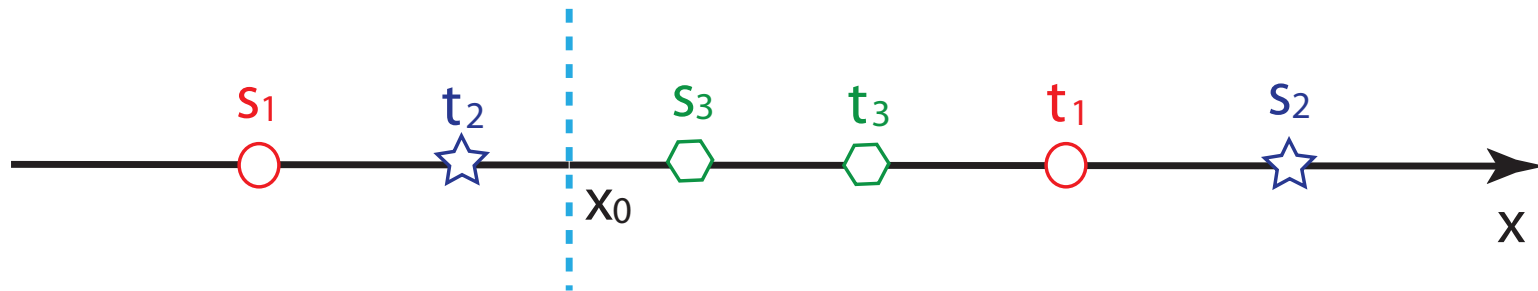
Theorem. For multiple unicast in space, network coding is equivalent to routing.

We prove the cost version of the multiple unicast conjecture in space.

$$\textit{Prove} : \sum_e \mathbf{f}_e \|e\| \geq \sum_i \mathbf{r}_i \mathbf{d}_i$$

\mathbf{f} : the underlying flow vector of a network coding solution.

3-6. Multiple Unicast in 1-D Space

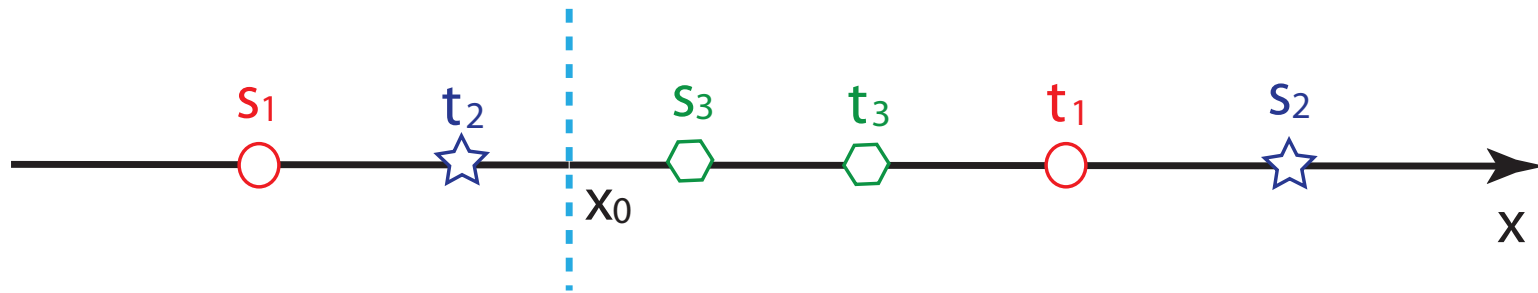


Throughput demand:

- $s_1 \rightarrow t_1: \mathbf{r}_1$
- $s_2 \rightarrow t_2: \mathbf{r}_2$
- $s_3 \rightarrow t_1: \mathbf{r}_3$

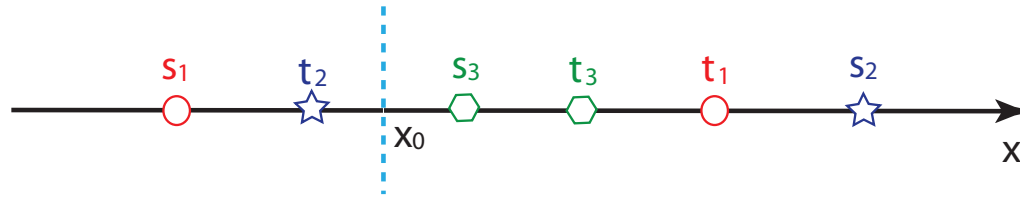
To prove: $\sum_e (\|e\|_1 \mathbf{f}_e) \geq \sum_i (\|s_i t_i\|_1 \mathbf{r}_i)$.

3-7. Multiple Unicast in 1-D Space



$$\begin{aligned} \mathbf{f}_{x_0} &\geq Demand((-\infty, x_0) \leftrightarrow (x_0, \infty)) \\ &= \mathbf{r}_1 + \mathbf{r}_2 \end{aligned}$$

3-8. Multiple Unicast in 1-D Space



$$\int_{x=-\infty}^{\infty} \mathbf{f}_x dx \geq \int_{x=-\infty}^{\infty} \text{Demand}((-\infty, x) \leftrightarrow (x, \infty)) dx$$

$$LFH = \sum_e (\|e\|_1 \mathbf{f}_e)$$

$$RHS = \sum_i \|s_i t_i\|_1 \mathbf{r}_i$$

Therefore: $\sum_e (\|e\|_1 \mathbf{f}_e) \geq \sum_i (\|s_i t_i\|_1 \mathbf{r}_i)$.

3-9. Multiple Unicast in h -D Space

To prove: $\sum_e(\mathbf{f}_e ||e||_h) \geq \sum_i(||s_i t_i||_h \mathbf{r}_i)$

Assume, b.w.o.c.: $\sum_e(\mathbf{f}_e ||e||_h) < \sum_i(||s_i t_i||_h \mathbf{r}_i)$

Find a unit 1-D vector \vec{p} , *s.t.*:

$$\sum_e(\mathbf{f}_e |e \cdot \vec{p}|) < \sum_i(|s_i t_i \cdot \vec{p}| \mathbf{r}_i)$$

Contradiction with result in 1-D.

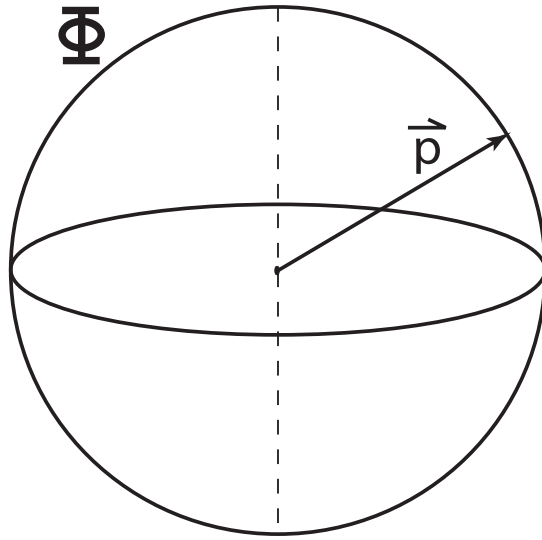
3-10: Multiple Unicast in h -D Space

Challenge: \vec{p} is hard to find!

Idea: enumerate all possible \vec{p} , by integrating over Φ .

Prove:

$$\iint_{\Phi} \sum_e (\mathbf{f}_e |e \cdot \vec{p}|) d\Phi < \iint_{\Phi} \sum_i (|s_i t_i \cdot \vec{p}| \mathbf{r}_i) d\Phi$$



3-11. Multiple Unicast in h -D Space

$$\begin{aligned}
 \iint_{\Phi} \sum_e (\mathbf{f}_e | e \cdot \vec{p} |) d\Phi &= {}_1 \sum_e \iint_{\Phi} \mathbf{f}_e | e \cdot \vec{p} | d\Phi \\
 &= {}_2 \sum_e \iint_{\Phi} \mathbf{f}_e \|e\|_h | \vec{1} \cdot \vec{p} | d\Phi \\
 &= {}_3 \sum_e (\mathbf{f}_e \|e\|_h) \iint_{\Phi} | \vec{1} \cdot \vec{p} | d\Phi
 \end{aligned}$$

3-12. Multiple Unicast in h -D Space

$$\begin{aligned}
 & \iint_{\Phi} \sum_i (\vec{s_i t_i} \cdot \vec{p}) \mathbf{r}_i d\Phi = \sum_i \iint_{\Phi} | \vec{s_i t_i} \cdot \vec{p} | d\Phi \\
 = & \sum_e \iint_{\Phi} (\|s_i t_i\|_h | \vec{1} \cdot \vec{p} |) \mathbf{r}_i d\Phi = \sum_i (\|s_i t_i\|_h \mathbf{r}_i) \iint_{\Phi} | \vec{1} \cdot \vec{p} | d\Phi
 \end{aligned}$$

By assumption: $\sum_e (\mathbf{f}_e \|e\|_h) < \sum_i (\|s_i t_i\|_h \mathbf{r}_i)$

We claim:

$$\iint_{\Phi} \sum_e (\mathbf{f}_e |e \cdot \vec{p}|) d\Phi < \iint_{\Phi} \sum_i (| \vec{s_i t_i} \cdot \vec{p} | \mathbf{r}_i) d\Phi$$

3-13. Multiple Unicast in h -D Space

We claim:

$$\iint_{\Phi} \sum_e (\mathbf{f}_e |e \cdot \vec{p}|) d\Phi < \iint_{\Phi} \sum_i (| \vec{s}_i t_i \cdot \vec{p} | \mathbf{r}_i) d\Phi$$

There must exist at least one particular \vec{p} , such that:

$$\sum_e (\mathbf{f}_e |e \cdot \vec{p}|) < \sum_i (| \vec{s}_i t_i \cdot \vec{p} | \mathbf{r}_i)$$

3-14. Multiple Unicast: Network *vs.* Space

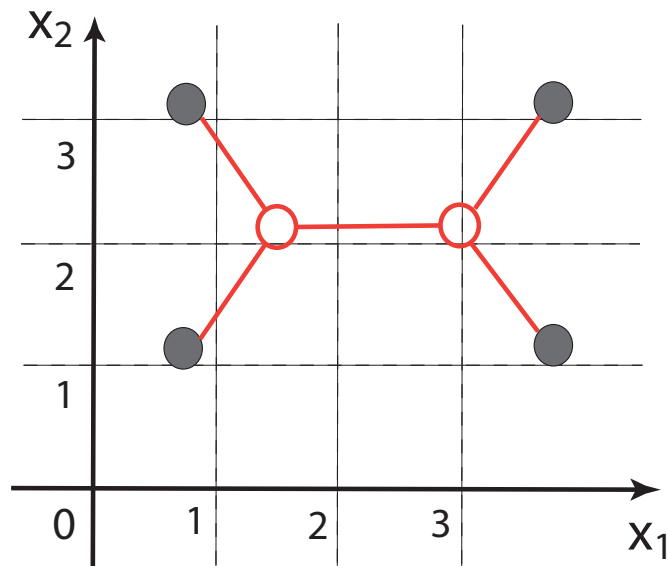
- **Isometric** (distance-preserving) **embedding** of graph metric?
- **Low-distortion embedding** of graph metric?
- Using a **Euclidean** or **non-Euclidean** geometry

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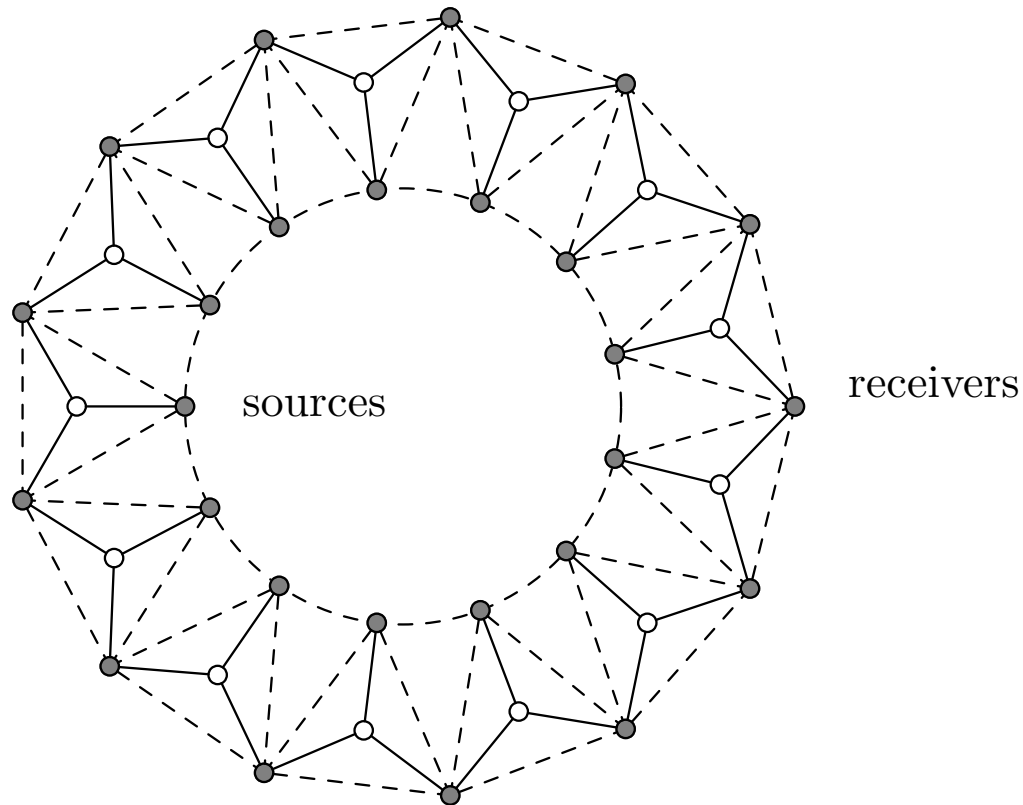
4-1. Multicast in Space

Is an optimal multicast solution in space always a **multicast tree** ?



4-2. Multicast in Space

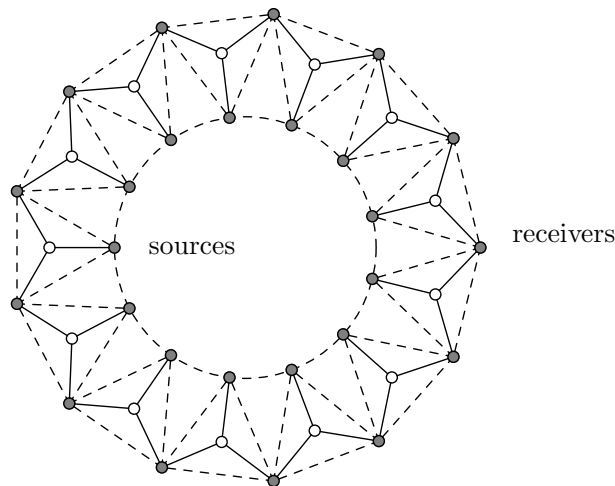
Is an optimal multicast solution in space always a **multicast tree**? — **No!**



4-3. Multicast in Space

Open problems:

- What is the **computational complexity** of the optimal multicast problem in space? **P?** **NP-hard?**
- Is this pattern **minimum**?



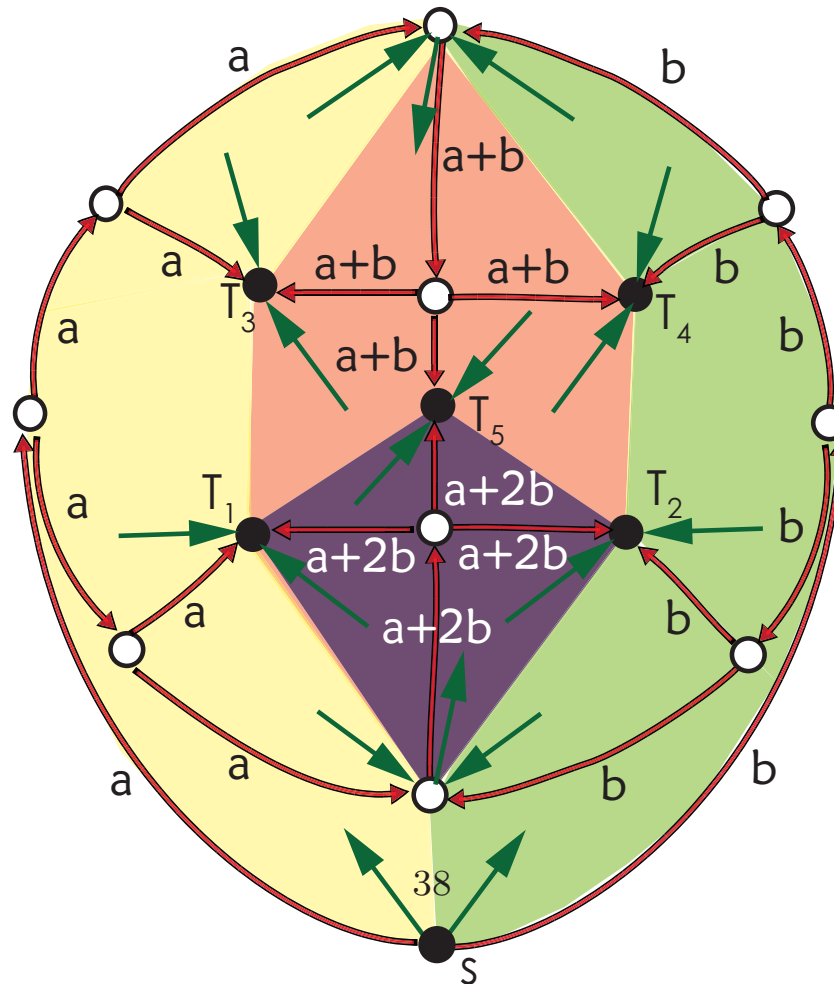
4-4. Multicasting 2 Flows in Space

Theorem. Multicasting 2 flows: cost advantage of network coding \leq the Steiner ratio

- **cost advantage:** the ratio of: min multicast tree cost over min multicast cost with network coding
- **Steiner ratio:** the ratio of: min spanning tree cost over min Steiner tree cost
- **The Gilbert-Pollak Conjecture:** the Steiner ratio in 2-D is at most $\frac{2}{\sqrt{3}} = 1.155$.

4-5. Multicasting 2 Flows in Space

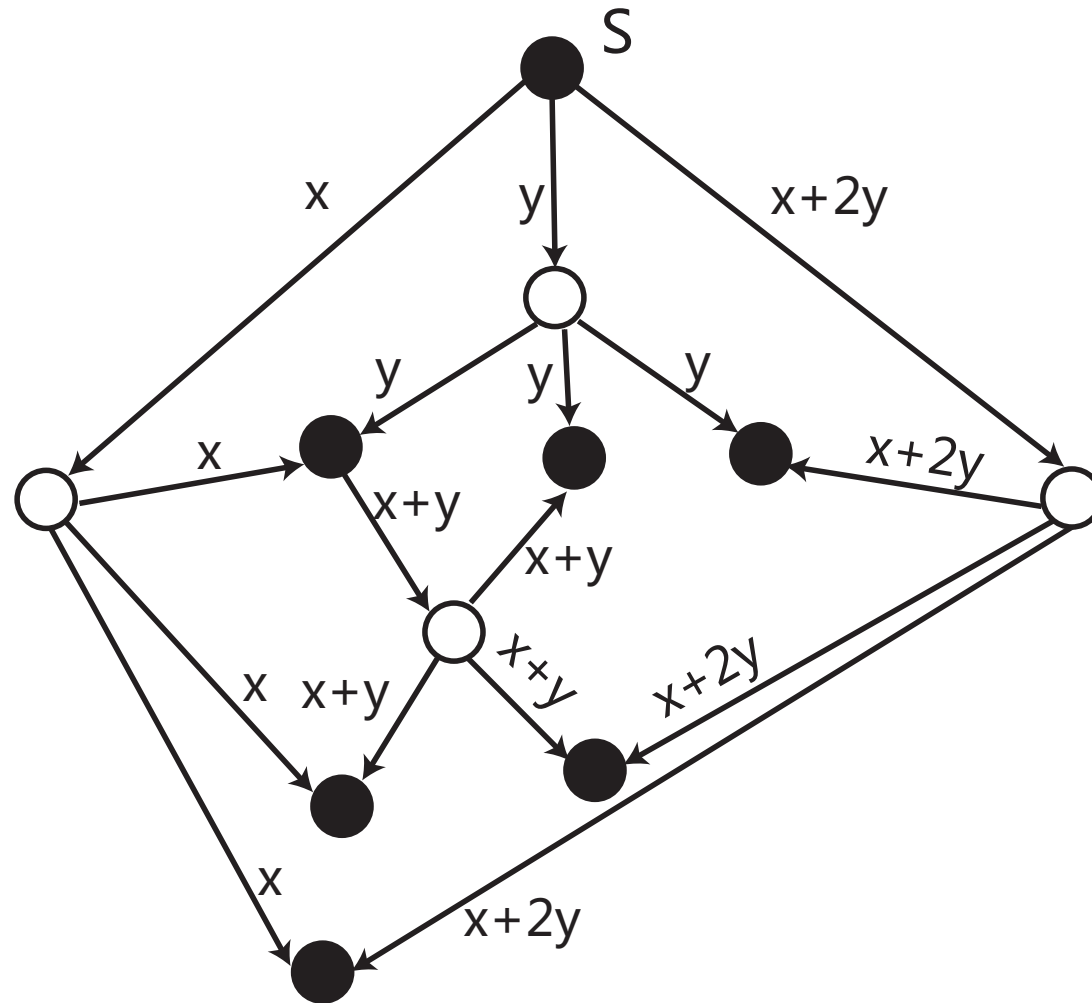
- Multicast flow decomposition
- Replace each component with a local spanning tree
- Resulting network is essentially a broadcast network



4-6. Bipartite Multicast Flow Structure

Theorem. Network coding solution has a **bipartite** structure: cost advantage of network coding ≤ 1.155 (unconditional).

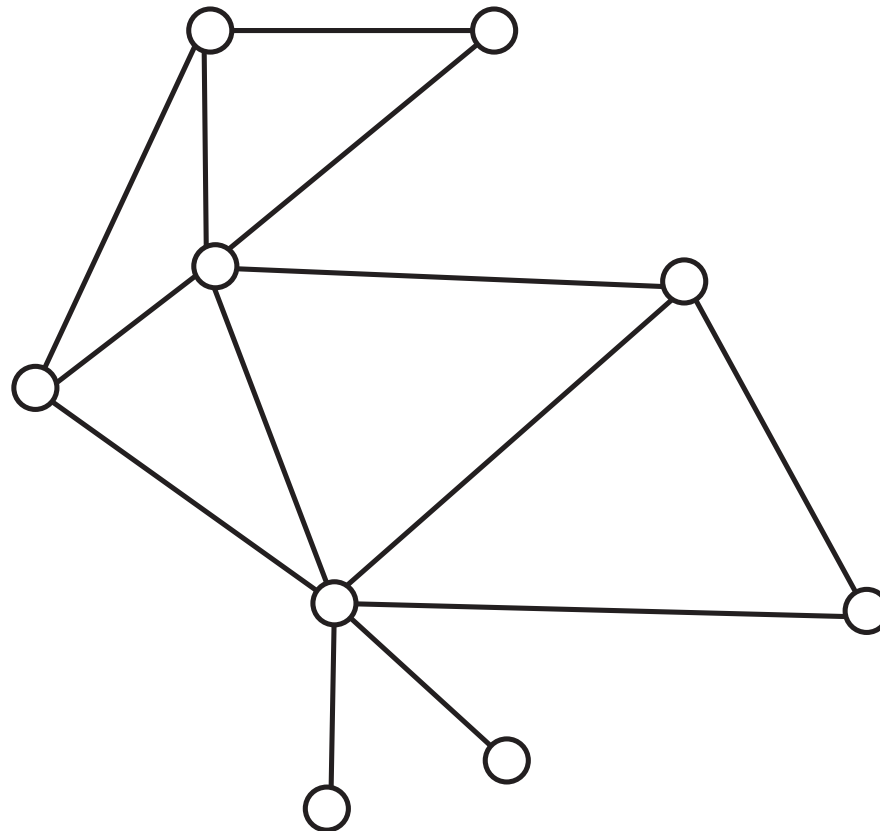
4-7. Bipartite Multicast Flow Structure



4.8. Multicast in Planar Networks

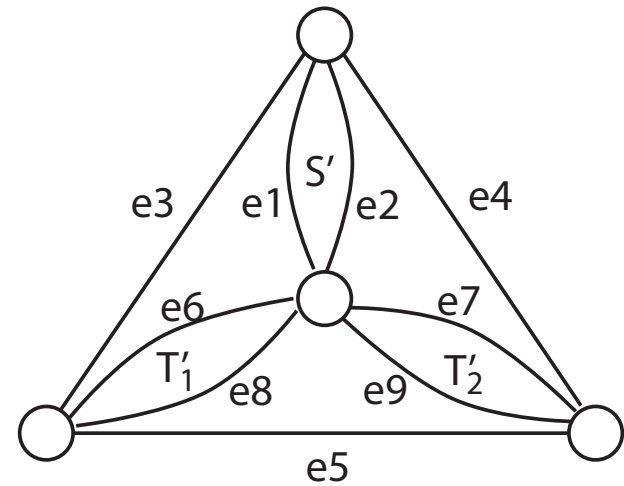
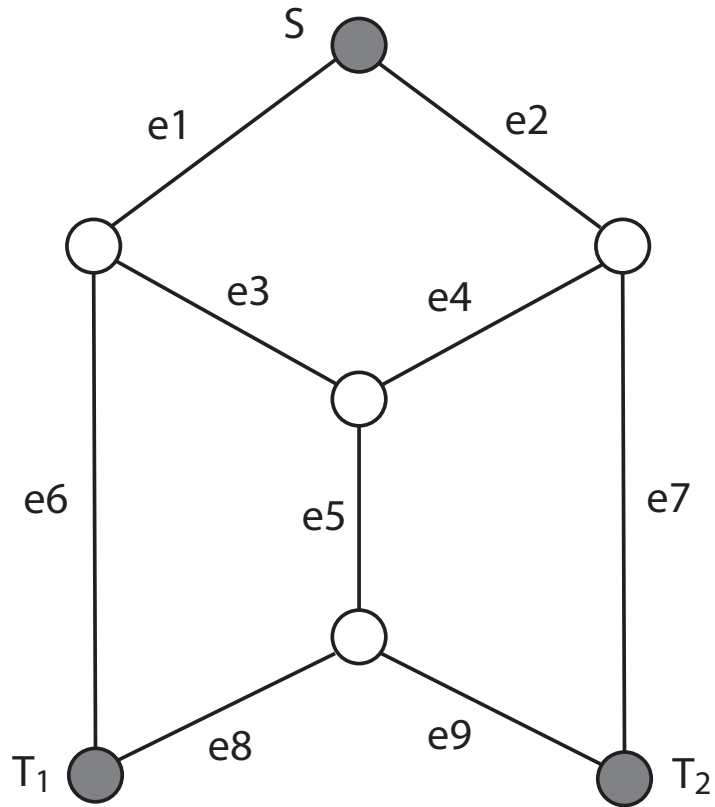
Outer-planar (all nodes on same face):

Network Coding = Routing



4.9. Multicast in Planar Networks

Terminals on Same Face: $GF(2)$ Sufficient?



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5-1. Conclusion

- Introduced the **space information flow** problem
- SIF models information network design
- Proved the multiple unicast conjecture in space
- Proved upper-bounds for benefits of multicast network coding in space

5-2. Open Problems for Space Information Flow

1. Optimal multicast in space: complexity, efficient algorithm design
2. Extend upper-bound analysis for multicast coding advantage in space
3. Wireless information flow in space, wireless network design
4. Multiple unicast, embedding?
5. Multicast in planar networks: small fields suffice?

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THE END